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Department of Electrical and Electronics Engineering

EE 5150–Transform Theory and Its Applications

Midterm Exam, Fall 2009

November 23th, 2009, 9:30-12:15 AM

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Q1) Determine the impulse response (**3p.**) and the step response of the following causal system (**3p.**). Are the system stable? (**3p.**)

$$y(n) = \frac{3}{4}y(n-1) - \frac{1}{8}y(n-2) + x(n)$$

$$Y(z) = \frac{X(z)}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$$

Impulse response: X(z)=1

$$Y(z) = \frac{2}{1 - \frac{1}{2}z^{-1}} - \frac{1}{1 - \frac{1}{4}z^{-1}}$$
$$h(n) = \left[2\left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n\right]u(n)$$

Step response: $X(z) = \frac{1}{1-z^{-1}}$

$$Y(z) = \frac{8/2}{1 - z^{-1}} - \frac{2}{1 - \frac{1}{2}z^{-1}} + \frac{1/3}{1 - \frac{1}{4}z^{-1}}$$
$$y(n) = \left[\frac{8}{3} - 2\left(\frac{1}{2}\right)^n - \frac{1}{3}\left(\frac{1}{4}\right)^n\right]u(n)$$

Since the poles of H(z) are inside the unit circle, the system is stable (poles at $z=\frac{1}{2},\frac{1}{4}$)

Q2) If X(z) is the z transform of x(n), show that (8p.)

$$Z{x^{*}(n)} = X^{*}(z^{*})$$

$$\sum_{n=-\infty}^{+\infty} x^*(n) z^{-n} = \sum_{n=-\infty}^{+\infty} [x(n)(z^*)^{-n}]^* = X^*(z^*)$$

Q3) Determine thr causal signal x(n) if its z transform, X(z), is given by (8p.)

$$X(z) = \frac{1 + 3z^{-1}}{1 + 3z^{-1} + 2z^{-2}}$$

$$X(z) = \frac{A}{1 - z^{-1}} + \frac{B}{1 - 2z^{-1}}$$

Hence; A=2, B=-1.

$$x(n) = [2(-1)^n - (-2)^n]u(n)$$

Q4) Let x(n) be a sequence with z transform X(z). Determine, in terms of X(z), the z transform of the following signal. **(8p.)**

$$\begin{aligned} x_1(n) &= x(2n) \\ X_1(z) &= \sum_{n=-\infty}^{+\infty} x_1(n) z^{-n} = \sum_{n=-\infty}^{+\infty} x_1(2n) z^{-n} = \sum_{k=-\infty}^{+\infty} x(k) z^{-k/2} \\ &= \sum_{k=-\infty}^{+\infty} \left[\frac{x(k) + (-1)^k x(k)}{2} \right] z^{-k/2}; \text{ k even} \\ &= \frac{1}{2} \sum_{k=-\infty}^{+\infty} x(k) z^{-k/2} + \frac{1}{2} \sum_{k=-\infty}^{+\infty} x(k) (-z^{1/2})^{-k} \\ &= \frac{1}{2} \left[X(\sqrt{z}) + X(-\sqrt{z}) \right] \end{aligned}$$

Q5) Determine the signal x(n) if its Fourier transform is a given as (6p.)

$$\begin{aligned} \mathbf{x}(\mathbf{n}) &= \frac{1}{2\pi} \left[\int_{\frac{8\pi}{10}}^{\frac{9\pi}{10}} \mathrm{e}^{\mathbf{j}\omega\mathbf{n}} \, \mathrm{d}\omega + \int_{\frac{-9\pi}{10}}^{\frac{-8\pi}{10}} \mathrm{e}^{\mathbf{j}\omega\mathbf{n}} \, \mathrm{d}\omega + 2 \int_{\frac{9\pi}{10}}^{\pi} \mathrm{e}^{\mathbf{j}\omega\mathbf{n}} \, \mathrm{d}\omega + 2 \int_{-\pi}^{\frac{-9\pi}{10}} \mathrm{e}^{\mathbf{j}\omega\mathbf{n}} \, \mathrm{d}\omega \right] \\ &= \frac{1}{2\pi} \left[\frac{1}{\mathrm{jn}} \left(\mathrm{e}^{\frac{\mathrm{jn}9\pi}{10}} - \mathrm{e}^{\frac{-\mathrm{jn}9\pi}{10}} - \mathrm{e}^{\frac{\mathrm{jn}8\pi}{10}} + \mathrm{e}^{\frac{-\mathrm{jn}8\pi}{10}} \right) + \frac{2}{\mathrm{jn}} \left(-\mathrm{e}^{\frac{\mathrm{jn}9\pi}{10}} + \mathrm{e}^{\frac{-\mathrm{jn}9\pi}{10}} + \mathrm{e}^{\mathrm{jn}\pi} - \mathrm{e}^{-\mathrm{jn}\pi} \right) \right] \\ &= \frac{1}{\mathrm{n\pi}} \left[\sin(\pi\mathbf{n}) - \sin\left(\frac{8\pi\mathbf{n}}{10}\right) - \sin\left(\frac{9\pi\mathbf{n}}{10}\right) \right] \end{aligned}$$

$$= -\frac{1}{n\pi} \left[\sin\left(\frac{4\pi n}{5}\right) + \sin\left(\frac{9\pi n}{10}\right) \right]$$

Q6) Consider a signal $x(n)=\{-1, 2, 3, 2, -1\}$ with Fourier transform $X(\omega)$. Compute the following quantities, without explicitly computing $X(\omega)$;

(a) X(0), (**2p.**) (b) Angle{X(
$$\omega$$
)}, (**2p.**) (c) X(π), (**2p.**) (d)

$$\int_{-\pi}^{\pi} |X(\omega)|^2 d\omega$$
, (**2p.**) (e) $\int_{-\pi}^{\pi} X(\omega) d\omega$ (**2p.**)
(a) x(0) = $\sum_n x(n) = -1$
(b) angle[X(ω)] = π for all ω
(c) x(π) = $\sum_{n=-\infty}^{+\infty} x(n)e^{-jn\pi} = \sum_n (-1)^n x(n) = -3 - 4 - 2 = -9$
(d) $\int_{-\pi}^{\pi} |X(\omega)|^2 d\omega = 2\omega \sum_n |x(n)|^2 = (2\pi)19 = 38\pi$
(e) X(0) = $\frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega) d\omega$
Then, $\int_{-\pi}^{\pi} X(\omega) d\omega = 2\pi X(0) = -6\pi$

Q7) Let $x_a(t)$ be an analog signal with bandwith B=3 kHz. We wish to use N=L^m-point DFT to compute the spectrum of the signal with a resolution less than or equal to 50 Hz. Determine the minimum sampling rate (2p.), the minimum number of required samples (2p.) and the minimum length of the analog signal record (2p.).

F₁=F_N=2B=6000 samples/sec.

 $T=1/F_{s}=1/6000$ $\frac{1}{LT} \le 50 \implies L \ge \frac{1}{50T} = \frac{6000}{50} = 120 \text{ samples}$ $LT = \frac{1}{6000} \cdot 120 = 0.02 \text{ sec.}$

Q8) Compute the N-point DFTs of the following signal. (8p.)

$$x(n) = \cos\left(\frac{2\pi}{N}k_0n\right), \qquad 0 \le n \le N-1$$

$$\begin{aligned} \mathbf{x}(n) &= \frac{1}{2} e^{j\frac{2\pi n}{N}k_0} + \frac{1}{2} e^{-j\frac{2\pi n}{N}k_0} = \mathbf{x}_1(n) + \mathbf{x}_2(n) \\ \mathbf{x}_1(k) &= \sum_{n=0}^{N-1} e^{j\frac{2\pi n}{N}k_0} e^{-j\frac{2k\pi n}{N}} = \sum_{n=0}^{N-1} e^{j\frac{-2\pi(k-k_0)n}{N}} \end{aligned}$$

From this result

$$X(k) = \frac{N}{2} [\delta(k - k_0) + \delta(k - N + k_0)]$$

Q9) The DCT is defined as

$$\theta(\mathbf{k}) = \frac{\sqrt{2}}{N} \sum_{n=0}^{N-1} \alpha(\mathbf{k}) \mathbf{x}(n) \cos\left[\frac{(2n+1)k\pi}{2N}\right] \qquad \mathbf{k}=0, 1, \dots, N-1$$
$$\mathbf{x}(n) = \frac{\sqrt{2}}{N} \sum_{n=0}^{N-1} \alpha(\mathbf{k}) \theta(\mathbf{k}) \cos\left[\frac{(2n+1)k\pi}{2N}\right] \qquad \mathbf{k}=0, 1, \dots, N-1$$

where $\alpha(0) = \frac{1}{\sqrt{2}}$ and $\alpha(k) = 1$; $k \neq 0$.

For N=2, calculate the DCT (2p.). What is the identical transform of this result included? (4p.)

$$C^{2} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ \cos(\pi/4) & \cos(3\pi/4) \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = L^{2}$$

The identical transform is Karhunen Loewe transform, L^2 .

Q10) Consider a stationary source with variance of unity and normalized autocorrelation ρ between neighboring samples

$$R_{xx} = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}$$

Find the eigenvalues, eigenvectors and the coefficients of KLT. (10p.)

$$\begin{vmatrix} 1 - \lambda & \rho \\ \rho & 1 - \lambda \end{vmatrix} = 0 \qquad \lambda_0 = 1 + \rho, \quad \lambda_1 = 1 - \rho$$
$$\begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \begin{bmatrix} I_0(0) \\ I_0(1) \end{bmatrix} = (1 + \rho) \begin{bmatrix} I_0(0) \\ I_0(1) \end{bmatrix}, \quad I_0(0) = -I_0(1)$$

Similarly, for I_1 , find that $I_1(0)=-I_1(1)$

If we scale the vectors, so that

 $I_0^2(0) + I_0^2(1) = I_1^2(0) + I_1^2(1) = 1$

The above equation show that the product of the eigenvalues λ_0 and λ_1 equals.

$$\begin{split} &\prod_{i=1}^{N-1}\lambda_i = \lambda_0\lambda_1 = 1-\rho^2 |R_{xx}| \qquad \text{and} \\ &R_{\theta\theta} \!=\! \begin{bmatrix} \lambda_0 & 0 \\ 0 & \lambda_1 \end{bmatrix} \!=\! \begin{bmatrix} 1+\rho & 0 \\ 0 & 1-\rho \end{bmatrix}\!\!, \qquad \text{hovewer } I_0 \text{ and } I_1 \text{ are the row of } L \text{ and for} \\ &\text{orthogonality, } LL^T \!=\! I. \end{split}$$

Therefore

$$L^{2} = (L^{T})^{2} = (L^{-1})^{2} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Q11) Find the Laplace transform of f(t). (6p.)

$$f(t) = e^{-2t} \cos(\sqrt{3}) - t^2 e^{-2t}$$

$$F(s) = L\{e^{-2t}\cos(\sqrt{3}) - t^2e^{-2t}\} = L\{e^{-2t}\cos(\sqrt{3})\} - L\{t^2e^{-2t}\} = \frac{3+2}{(s+2)^2+3} - \frac{2}{(s+2)^3}$$

Q12) Laplace transforms are useful for solving linear differential equations that arise in many settings. Consider a linearized model of a motor with a torque control system, for example, where the actual torque of the motor relative to a desired torque is described by the following Laplace transform.

$$H(s) = \frac{\frac{k_p}{L}\left(s + \frac{k_I}{k_p}\right)}{s^2 + \frac{k_p}{L}s + \frac{k_I}{L}}$$

where L=1 mH=inductance of motor windings, k_p =gain for proportional feedback, k_i =gain for integral feedback. The inverse Laplace transform of H(s) contains multiplicative factors of the form e^{-at} that determine how fast time waveforms decay to zero. This decay corresponds to how rapidly the motor torque reaches a desired value. A faster decay is desirable. Equal roots, (i.e. critical damping), is optimal if vibration (oscillatory solutions) must be eliminated. Find the inverse Laplace transform of H(s) for the values; a=1.6k, k_i =2.56G. (10p.)

$$H(s) = \frac{\frac{k_{p}}{L}\left(s + \frac{k_{I}}{k_{p}}\right)}{s^{2} + \frac{k_{p}}{L}s + \frac{k_{I}}{L}} = \frac{\frac{a}{2}\left(s + \frac{a}{2}\right)}{(s + a)^{2}}$$

We can factor out an s+a fron the top, as follows.

$$H(s) = \frac{\frac{a}{2}\left(s+a-\frac{a}{2}\right)}{(s+a)^2} = \frac{a}{2}\left(\frac{1}{s+a}-\frac{a}{2}\cdot\frac{1}{(s+a)^2}\right)$$

The inverse Laplace transform now follows.

$$h(t) = \frac{a}{2} \left(e^{-at} - \frac{a}{2} t e^{-at} \right) = \frac{a}{2} e^{-at} \left(1 - \frac{a}{2} t \right)$$

Using the value of a, we have the numerical answer.

h(t)=800e^{-800t}(1-800t)=800e^{-t/1.25ms}(1-t/1.25ms)

Q13) Find the Fourier sine transform of e^{-x} , $x \ge 0$ (**2p.**). By using this result, show that (**3p.**)

$$\int_0^\infty \frac{x \sin(mx)}{x^2 + 1} dx = \frac{\pi}{2} e^{-m}, \quad m > 0$$

 $\frac{\sqrt{2}}{\pi} \Big[\frac{\alpha}{(1+\alpha^2)} \Big]$